

# Lecture 6: Exercise 3

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## Explanation

Here we are practicing deriving the equation of motion from a given Lagrangian.

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## Hint

The process is to turn the crank of the machine that is the Lagrangian Method given the Lagrangian:

1. Calculate  $\frac{\partial L}{\partial x_i}$
2. Calculate  $\frac{\partial L}{\partial \dot{x}_i}$
3. Calculate  $\frac{d}{dt} \left( \frac{\partial L}{\partial \dot{x}_i} \right)$
4. Substitute the calculated values into the Euler-Lagrange Equation:  $\frac{d}{dt} \left( \frac{\partial L}{\partial \dot{x}_i} \right) = \frac{\partial L}{\partial x_i}$

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## Answer

We begin by writing the Lagrangian, Eq. (12)

$$L = \frac{m}{2} (\dot{X}^2 + \dot{Y}^2) + \frac{m\omega^2}{2} (X^2 + Y^2) + m\omega (\dot{X}Y - \dot{Y}X)$$

We now need to calculate  $\frac{\partial L}{\partial x_i}$ , since we have  $X$  and  $Y$  we write

$$\frac{\partial L}{\partial X} = \frac{\partial}{\partial X} \left[ \frac{m}{2} (\dot{X}^2 + \dot{Y}^2) + \frac{m\omega^2}{2} (X^2 + Y^2) + m\omega (\dot{X}Y - \dot{Y}X) \right]$$

this becomes

$$\frac{\partial L}{\partial X} = \frac{\partial}{\partial X} \left[ \frac{m\omega^2}{2} (X^2 + Y^2) + m\omega (\dot{X}Y - \dot{Y}X) \right]$$

We use the sum rule

$$\frac{\partial L}{\partial X} = \frac{\partial}{\partial X} \frac{m\omega^2}{2} (X^2 + Y^2) + \frac{\partial}{\partial X} m\omega (\dot{X}Y - \dot{Y}X)$$

We can treat  $m\omega$  and  $m\omega^2/2$  as constants and use the constant multiple rule

$$\frac{\partial L}{\partial X} = \frac{m\omega^2}{2} \frac{\partial}{\partial X} (X^2 + Y^2) + m\omega \frac{\partial}{\partial X} (\dot{X}Y - \dot{Y}X)$$

we can expand this using the sum rule,

$$\frac{\partial L}{\partial X} = \frac{m\omega^2}{2} \frac{\partial}{\partial X} X^2 + \frac{m\omega^2}{2} \frac{\partial}{\partial X} Y^2 + m\omega \frac{\partial}{\partial X} \dot{X}Y - m\omega \frac{\partial}{\partial X} \dot{Y}X$$

if there is no  $X$  the third term vanishes,

$$\frac{\partial L}{\partial X} = \frac{m\omega^2}{2} \frac{\partial}{\partial X} X^2 - m\omega \frac{\partial}{\partial X} \dot{Y}X$$

we again apply the constant multiple rule,

$$\frac{\partial L}{\partial X} = \frac{m\omega^2}{2} \frac{\partial}{\partial X} X^2 - m\omega \dot{Y} \frac{\partial}{\partial X} X$$

since  $\partial X / \partial X = 1$ , and we apply the power rule,

$$\frac{\partial L}{\partial X} = m\omega^2 X - m\omega \dot{Y}$$

We do the same thing for  $Y$ ,

$$\frac{\partial L}{\partial Y} = \frac{\partial}{\partial Y} \left[ \frac{m}{2} (\dot{X}^2 + \dot{Y}^2) + \frac{m\omega^2}{2} (X^2 + Y^2) + m\omega (\dot{X}Y - \dot{Y}X) \right]$$

$$\frac{\partial L}{\partial Y} = \frac{\partial}{\partial Y} \left[ \frac{m\omega^2}{2} (X^2 + Y^2) + m\omega (\dot{X}Y - \dot{Y}X) \right]$$

$$\frac{\partial L}{\partial Y} = \frac{m\omega^2}{2} \frac{\partial}{\partial Y} (X^2 + Y^2) + m\omega \frac{\partial}{\partial Y} (\dot{X}Y - \dot{Y}X)$$

$$\frac{\partial L}{\partial Y} = \frac{m\omega^2}{2} \frac{\partial}{\partial Y} X^2 + \frac{m\omega^2}{2} \frac{\partial}{\partial Y} Y^2 + m\omega \frac{\partial}{\partial Y} \dot{X}Y - m\omega \frac{\partial}{\partial Y} \dot{Y}X$$

$$\frac{\partial L}{\partial Y} = \frac{m\omega^2}{2} \frac{\partial}{\partial Y} Y^2 + m\omega \frac{\partial}{\partial Y} \dot{X}Y$$

$$\frac{\partial L}{\partial Y} = m\omega^2 Y + m\omega \dot{X}$$

We then calculate  $\partial L / \partial \dot{X}$

$$\frac{\partial L}{\partial \dot{X}} = \frac{\partial}{\partial \dot{X}} \left[ \frac{m}{2} (\dot{X}^2 + \dot{Y}^2) + \frac{m\omega^2}{2} (X^2 + Y^2) + m\omega (\dot{X}Y - \dot{Y}X) \right]$$

We have one term that vanishes

$$\frac{\partial L}{\partial \dot{X}} = \frac{\partial}{\partial \dot{X}} \left[ \frac{m}{2} (\dot{X}^2 + \dot{Y}^2) + m\omega (\dot{X}Y - \dot{Y}X) \right]$$

we can expand this using the sum rule,

$$\frac{\partial L}{\partial \dot{X}} = \frac{\partial}{\partial \dot{X}} \frac{m}{2} (\dot{X}^2 + \dot{Y}^2) + \frac{\partial}{\partial \dot{X}} m\omega (\dot{X}Y - \dot{Y}X)$$

then we use the constant multiple rule

$$\frac{\partial L}{\partial \dot{X}} = \frac{m}{2} \frac{\partial}{\partial \dot{X}} (\dot{X}^2 + \dot{Y}^2) + m\omega \frac{\partial}{\partial \dot{X}} (\dot{X}Y - \dot{Y}X)$$

we again use the sum rule

$$\frac{\partial L}{\partial \dot{X}} = \frac{m}{2} \frac{\partial}{\partial \dot{X}} \dot{X}^2 + \frac{m}{2} \frac{\partial}{\partial \dot{X}} \dot{Y}^2 + m\omega \frac{\partial}{\partial \dot{X}} \dot{X}Y - m\omega \frac{\partial}{\partial \dot{X}} \dot{Y}X$$

two terms vanish,

$$\frac{\partial L}{\partial \dot{X}} = \frac{m}{2} \frac{\partial}{\partial \dot{X}} \dot{X}^2 + m\omega \frac{\partial}{\partial \dot{X}} \dot{X}Y$$

so

$$\frac{\partial L}{\partial \dot{X}} = m\dot{X} + m\omega Y$$

We then calculate  $\partial L / \partial \dot{Y}$

$$\frac{\partial L}{\partial \dot{Y}} = \frac{\partial}{\partial \dot{Y}} \left[ \frac{m}{2} (\dot{X}^2 + \dot{Y}^2) + \frac{m\omega^2}{2} (X^2 + Y^2) + m\omega (\dot{X}Y - \dot{Y}X) \right]$$

$$\frac{\partial L}{\partial \dot{Y}} = \frac{\partial}{\partial \dot{Y}} \left[ \frac{m}{2} (\dot{X}^2 + \dot{Y}^2) + m\omega (\dot{X}Y - \dot{Y}X) \right]$$

$$\frac{\partial L}{\partial \dot{Y}} = \frac{\partial}{\partial \dot{Y}} \frac{m}{2} (\dot{X}^2 + \dot{Y}^2) + \frac{\partial}{\partial \dot{Y}} m\omega (\dot{X}Y - \dot{Y}X)$$

$$\frac{\partial L}{\partial \dot{Y}} = \frac{m}{2} \frac{\partial}{\partial \dot{Y}} \dot{X}^2 + \frac{m}{2} \frac{\partial}{\partial \dot{Y}} \dot{Y}^2 + m\omega \frac{\partial}{\partial \dot{Y}} \dot{X}Y - m\omega \frac{\partial}{\partial \dot{Y}} \dot{Y}X$$

$$\frac{\partial L}{\partial \dot{Y}} = \frac{m}{2} \frac{\partial}{\partial \dot{Y}} \dot{Y}^2 - m\omega \frac{\partial}{\partial \dot{Y}} \dot{Y}X$$

$$\frac{\partial L}{\partial \dot{Y}} = m\dot{Y} - m\omega X$$

This give us the canonical momentum vector

$$\vec{p} = (m\dot{X} + m\omega Y, m\dot{Y} - m\omega X)$$

We take the time derivative of this to get the generalized force,

$$\begin{aligned}
\frac{d}{dt} \vec{p} &= \frac{d}{dt} (m \dot{X} + m \omega Y, m \dot{Y} - m \omega X) \\
\frac{d}{dt} \vec{p} &= \left[ \frac{d}{dt} (m \dot{X} + m \omega Y), \frac{d}{dt} (m \dot{Y} - m \omega X) \right] \\
\frac{d}{dt} \vec{p} &= \left[ \left( \frac{d}{dt} m \dot{X} + \frac{d}{dt} m \omega Y \right), \left( \frac{d}{dt} m \dot{Y} - \frac{d}{dt} m \omega X \right) \right] \\
\frac{d}{dt} \vec{p} &= (m \ddot{X} + m \omega \dot{Y}, m \ddot{Y} - m \omega \dot{X})
\end{aligned}$$

We now write the two equations of motion

$$\begin{aligned}
\frac{d}{dt} \left( \frac{\partial L}{\partial \dot{X}} \right) &= \frac{\partial L}{\partial X} \Rightarrow m \ddot{X} + m \omega \dot{Y} = m \omega^2 X - m \omega \dot{Y} \Rightarrow \ddot{X} + \omega \dot{Y} = \omega^2 X - \omega \dot{Y} \Rightarrow \ddot{X} = \omega^2 X - 2\omega \dot{Y} \\
\frac{d}{dt} \left( \frac{\partial L}{\partial \dot{Y}} \right) &= \frac{\partial L}{\partial Y} \Rightarrow m \ddot{Y} - m \omega \dot{X} = m \omega^2 Y + m \omega \dot{X} \Rightarrow \ddot{Y} - \omega \dot{X} = \omega^2 Y + \omega \dot{X} \Rightarrow \ddot{Y} = \omega^2 Y + 2\omega \dot{X}
\end{aligned}$$