

# On the Cowling Approximation: A Verification of the Method via Functional and Asymptotic Analysis

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Midwest Relativity Meeting, Oct. 24, 2020  
University of Notre Dame

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# The system of Equations

## Perturbation and Linearization.

We introduce the basic principles [AC-DK, Cor, LW, SVH, T]

Perturbation quantities  $\xi, \eta$ :

- Lagrangian displacement vector  $\vec{\xi}$
- $\vec{\xi} = \xi \hat{r} + \nabla_h \eta$  (spherical coords.)  $\xi$  is aka  $\delta r$ .
- $\nabla_h \eta = \left( 0, \frac{1}{r} \frac{\partial \eta}{\partial \theta}, \frac{1}{r \sin \theta} \frac{\partial \eta}{\partial \phi} \right)$
- Spheroidal normal modes  $(\nabla \times \vec{\xi})_r = \vec{0}$

## Governing Equations - Isentropic Model.

Physical quantities:  $\rho$  density,  $P$  pressure,  $V$  potential,  $\vec{g}$  acceleration due to gravity,  $\Gamma_1$  is adiabatic exponent.

Linearized Governing Equations: Expressed in terms of  $\vec{\xi}$ :

- $\delta\rho = -\nabla \cdot (\rho\vec{\xi})$  (mass conservation)
- $\delta P = -\Gamma_1 P \nabla \cdot \vec{\xi} - \vec{\xi} \cdot \nabla P$  (isentropic equation of state)
- $\frac{1}{\rho} \nabla P = \vec{g} = -\nabla V$  (equilibrium)
- $\nabla^2 \delta V = -4\pi G \nabla \cdot (\rho\vec{\xi})$  (Poisson's equation).

( $\delta$  Eulerian perturbation; ' derivative wrt  $r$ )

- Expansions in terms of spherical harmonics  $Y_\ell^m$ .  
Superposition of modes of the form

$$e^{i(\sigma_\ell t + m\phi)} \eta_{l,m}(r) Y_\ell^m(\theta, \phi)$$

$$e^{i(\sigma_\ell t + m\phi)} \xi_{l,m}(r) Y_\ell^m(\theta, \phi)$$

- After separation of variables, equations decouple w.r.t  $\ell$ .
- Spheroidal normal modes are degenerate w.r.t.  $m$ .

## Resulting System - LW Formulation

Subscripts are dropped, understanding that *frequency*  $\sigma$  and dependent variables depend on *degree*  $\ell$

$$\frac{du}{dr} = \frac{g}{c^2}u + \left[ \frac{\ell(\ell+1)}{\sigma^2} - \frac{r^2}{c^2} \right] y + \frac{r^2}{c^2}\Phi \quad (1)$$

$$\frac{dy}{dr} = \frac{\sigma^2 - N^2}{r^2}u + \frac{N^2}{g}y - \frac{d}{dr}\Phi(r) \quad (2)$$

$$\frac{1}{r^2} \frac{d}{dr} \left( r^2 \frac{d\Phi}{dr} \right) - \frac{\ell(\ell+1)}{r^2} \Phi = 4\pi G\rho \left( \frac{N^2}{r^2 g} u + \frac{1}{c^2} y \right) \quad (3)$$

(Ledoux and Walraven)

Here

- $u \stackrel{\text{def}}{=} r^2 \xi$ ,  $y \stackrel{\text{def}}{=} \frac{\delta p}{\rho}$ ,  $\Phi \stackrel{\text{def}}{=} \delta V$
- $c = \sqrt{\frac{\Gamma_1 p}{\rho}}$  is the speed of sound
- $N^2 = -g \left( \frac{g}{c^2} + \frac{d \ln \rho}{dr} \right)$  :  $N$  is the *Brunt-Väisälä frequency*
- Boundary conditions at stellar center  $r = 0$  and stellar surface  $r = R$ , typically.
- Boundary-value problems in terms of  $\sigma$  form (non-linear) eigenvalue problems for each  $\ell$ :  $\sigma$  called an *eigenfrequency*.

# Alternative Formulation - ES

$$\frac{d u}{d r} = \frac{g}{c^2} u + \left[ \ell(\ell + 1) - \sigma^2 \frac{r^2}{c^2} \right] \eta + \frac{r^2}{c^2} \Phi \quad (4)$$

$$\frac{d \eta}{d r} = \frac{1}{r^2} \left( 1 - \frac{N^2}{\sigma^2} \right) u + \frac{N^2}{g} \eta - \frac{N^2}{\sigma^2 g} \Phi(r) \quad (5)$$

$$\frac{1}{r^2} \frac{d}{d r} \left( r^2 \frac{d \Phi}{d r} \right) - \left[ \frac{\ell(\ell + 1)}{r^2} - \frac{4\pi G \rho}{c^2} \right] \Phi = 4\pi G \rho \left( \frac{N^2}{r^2 g} u + \frac{\sigma^2}{c^2} \eta \right) \quad (6)$$

(Eisenfeld and Smeyers)



# Cowling Approximation

In the so-called Cowling approximation, the perturbation  $\Phi = \delta V$  is neglected in (1), (2) or in (4), (5) leaving

$$\frac{du}{dr} = \frac{g}{c^2} u + \left[ \frac{\ell(\ell+1)}{\sigma^2} - \frac{r^2}{c^2} \right] y$$

$$\frac{dy}{dr} = \frac{\sigma^2 - N^2}{r^2} u + \frac{N^2}{g} y$$

or

$$\frac{du}{dr} = \frac{g}{c^2} u + \left[ \ell(\ell+1) - \sigma^2 \frac{r^2}{c^2} \right] \eta$$

$$\frac{d\eta}{dr} = \frac{1}{r^2} \left( 1 - \frac{N^2}{\sigma^2} \right) u + \frac{N^2}{g} \eta$$

(resp.).

# Main Technique

We apply analysis of equations of more abstract form

$$\mathcal{L}\vec{x} = F(\vec{x}) + \vec{f} \quad (7)$$

where

- $F$  is symmetric on a real Hilbert space  $\mathbb{H}$  (eg.  $L^2(a, b)$ ).
- $\mathcal{L}$  self-adjoint (SA) on a subspace  $\mathcal{H}$  dense in  $\mathbb{H}$  :  $\mathcal{H}$  is called a *core* for  $\mathcal{L}$ .
- $\mathcal{H}$  may depend on SA boundary conditions imposed.
- $L^2$ : Think QM; integral inner product;  $\|\vec{x}\| = \sqrt{\langle \vec{x}, \vec{x} \rangle}$

# A Theorem by Amann

We will be applying the following theorem which is a special case (linear version) of Theorem 2.6 of [A]

## Theorem 2.1

Suppose the following hold for some  $\gamma > 0$  :

- $\langle (\mathcal{L} - F)\vec{x}, \vec{x} \rangle \leq -\gamma \|\vec{x}\|^2 \quad \forall \vec{x} \in \mathcal{H}_1$
- $\langle (\mathcal{L} - F)\vec{x}, \vec{x} \rangle \geq \gamma \|\vec{x}\|^2 \quad \forall \vec{x} \in \mathcal{H}_2$ ;
- $\mathcal{H} = \mathcal{H}_1 \oplus \mathcal{H}_2$

Then, there is a unique solution  $\vec{y} \in \mathcal{H}$  to (7); and, the solution satisfies

$$\|\vec{y}\| \leq \frac{2}{\gamma} \|\vec{f}\|$$

# Particulars

$\mathcal{L}$  and  $F$  have complete set of eigenfunctions

- $\{\psi_k\}_{k=1}^n$  and  $\{\phi_k\}_{k=1}^n$  with associated eigenvalues  $\{\lambda_k\}_{k=1}^n$  and  $\{\nu_k\}_{k=1}^n$ , resp.
- The spectra are discrete (pure-point) where

$$\lambda_k \searrow -\infty; \nu_k \nearrow 0$$

- Slight modification allows assumption of only non-zero eigenvalues.
- We can take  $\gamma = \text{dist}(\text{spec}(\mathcal{L}), \text{spec}(F)) > 0$

# Enter Asymptotics

- We see homogeneous systems

$$\frac{d}{dr}X = \sigma^2 AX$$

for large  $\sigma > 0$  where  $A = \Lambda_0 + \sigma^{-2}\Lambda_1 + \sigma^{-4}\Lambda_2$

- Apply asymptotic methods [CL] in combination with main theorem.
- Form non-homogeneous equations to effectively decouple.
- Change of variables and alternative parameterizations pursued.

## Adiabatic Equilibrium: Simplifying Assumption

We will set

$$N^2 = 0$$

on  $[a, b]$  *adiabatic equilibrium* whereby

- aka isentropic equilibrium (explicitly assume reversibility)
- $g = -c^2 \frac{d \ln \rho}{dr}$
- A very convenient integrating factor results.

## Recast ES

The first two equations of the ES system

$$\frac{d u}{d r} - \frac{g}{c^2} u - \left[ \ell(\ell + 1) - \sigma^2 \frac{r^2}{c^2} \right] \eta = \frac{r^2}{c^2} \Phi \quad (8)$$

$$\frac{d \eta}{d r} - \frac{1}{r^2} u = 0 \quad (9)$$

Rewrite ES as

$$\frac{d}{d r} \left( r^2 \rho(r) \frac{d \eta}{d r} \right) - \left[ \ell(\ell + 1) - \sigma^2 \frac{r^2}{c^2} \right] \rho(r) \eta = \frac{r^2}{c^2} \Phi$$

$$\frac{d}{d r} \left( r^2 \frac{d \Phi}{d r} \right) - \left[ \ell(\ell + 1) - \frac{4\pi G \rho r^2}{c^2} \right] \Phi = 4\pi G \rho \left( \frac{\sigma^2 r^2}{c^2} \eta \right)$$

Imposing SA boundary conditions, the LHS of each equation is of S-L form which we will write as

$$\mathcal{J}_{l\sigma}\eta = \frac{r^2}{c^2}\rho\Phi$$
$$\mathcal{L}_\ell\Phi = 4\pi G\rho\left(\frac{\sigma^2 r^2}{c^2}\eta\right)$$

- Operators  $\mathcal{J}_{l\sigma}$  and  $\mathcal{L}_\ell$  are S-L type.
- Combining equations to obtain:  $\mathcal{L}_\ell\Phi = \sigma^2 F(\Phi) + \sigma^2 f_0$
- Indeed,  $F$  is symmetric as above.



## Recast LW

Now set  $N = 0$  in the LW system, (1)(2)(3)

$$\frac{du}{dr} = \frac{g}{c^2}u + \left[ \frac{\ell(\ell+1)}{\sigma^2} - \frac{r^2}{c^2} \right] y + \frac{\ell(\ell+1)}{\sigma^2}\Phi \quad (10)$$

$$\frac{dy}{dr} = \frac{\sigma^2}{r^2}u - \frac{d\Phi}{dr} \quad (11)$$

$$\frac{d}{dr} \left( r^2 \frac{d\Phi}{dr} \right) - \ell(\ell+1)\Phi = 4\pi G \frac{\rho r^2}{c^2} y \quad (12)$$

## Change Variables and Parameters

And, setting  $v \stackrel{\text{def}}{=} \frac{1}{r}u$ ,  $\zeta^2 \stackrel{\text{def}}{=} \ell(\ell + 1)$  and  $\sigma^2 \stackrel{\text{def}}{=} z\zeta$ , equations (10) and (11) become

$$\frac{dv}{dr} = \left( \frac{g}{c^2} - \frac{1}{r} \right) v + \left[ \frac{\zeta}{zr} - \frac{r}{c^2} \right] y + \frac{\zeta}{zr} \phi$$

$$\frac{dy}{dr} = \frac{\zeta z}{r} v - \frac{d\phi}{dr}$$

respectively.

## LW in Partial Matrix Form

We then form a system of equations in matrix form

$$\frac{d}{dr} Y = \zeta AY + \mathfrak{G} \text{ where}$$

$$Y = \begin{bmatrix} v \\ y \end{bmatrix}, \quad \mathfrak{G} = \begin{bmatrix} \frac{\zeta}{zr} \Phi \\ -\frac{d\Phi}{dr} \end{bmatrix}$$

Then,  $A = A_0 + \frac{1}{\zeta} A_1$  for

$$A_0 = \frac{1}{r} \begin{bmatrix} 0 & \frac{1}{z} \\ z & 0 \end{bmatrix} \text{ and } A_1 = \begin{bmatrix} \frac{rg-c^2}{rc^2} & -\frac{r}{c^2} \\ 0 & 0 \end{bmatrix}$$

Much of the analysis methods for ES will also be applied here.

## ES Results: Large $\ell$ , Bounded $\sigma$

- For sufficiently large  $\ell$ , there results

$$\|\Phi_p\| \leq \frac{2\sigma^2}{\gamma} \|f_0\| \leq \sigma^2 \frac{\text{Const.}}{\gamma} \|\eta_0\|$$

- Indeed,  $\|\Phi_p\| = O(\ell^{-2})$  as  $\ell \rightarrow \infty$
- General idea:  $\Phi \approx \Phi_0$  in norm for large  $\ell$
- In turn,  $\Phi \approx 0$  verifies Cowling.

## Large $\sigma$ ; Matrix Form

We apply asymptotic estimates wrt large  $\sigma$

- Change of variables  $w \stackrel{\text{def}}{=} \rho\sigma^{-1}u$  to recast (8) & (9)
- Leads to non-homogeneous system of the form
$$\vec{Y}' = \sigma\mathbf{A}_0\vec{Y} + \sigma^{-1}\mathbf{A}_2 + \sigma^{-1}\vec{f}$$
- Apply asymptotic methods together with main estimate
- Check calculations via Mathematica using method related to [W]. (See Appendix.)

# Insert Asymptotics

We arrive at a particular solution satisfying

$$\eta_p = \frac{\sqrt{c(r)}}{\sigma r \sqrt{\rho(r)}} \sin(\sigma\theta(r)) \int_a^r t \sqrt{\frac{\rho(t)}{c^3(t)}} \cos(\sigma\theta(t)) \Phi(t) dt +$$

$$\frac{\sqrt{c(r)}}{\sigma r \sqrt{\rho(r)}} \cos(\sigma\theta(r)) \int_r^b t \sqrt{\frac{\rho(t)}{c^3(t)}} \sin(\sigma\theta(t)) \Phi(t) dt + O(\sigma^{-3})$$

$$\stackrel{\text{def}}{=} \sigma^{-1} \mathcal{W}(\Phi) + O(\sigma^{-3})$$

for  $\theta(r) \stackrel{\text{def}}{=} \int^r \frac{1}{c(r)} dr$

# Sharper Estimate

We can sharpen the estimate if a symmetric  $F$  can be found:

- $\frac{r^2 \rho}{c^2} \mathcal{W}$  is symmetric
- $\gamma \geq \alpha$  and  $\alpha = O(\sigma^2)$  as  $\sigma \rightarrow +\infty$
- $\frac{\sigma^2}{\gamma} = O(1)$
- Obtain

$$\|\Phi_\rho\| \leq C_1 \frac{1}{\sigma \gamma} + C_2 \|\eta_0\|$$

with  $\gamma^{-1} = O(\sigma^{-2})$

- Since  $\theta'$  is positive on  $[a, b]$ , we find  $\|\eta_0\| = O(\sigma^{-1})$

LW:  $\ell$  and  $\sigma^2$  Large but Comparable.

We find a particular  $y$  with estimates uniform  $r$  and  $\zeta$ :  $y_p =$

$$\frac{1}{2} \left[ r^{\zeta-1/2} e^{\mathcal{I}^-(r)} \int_a^r \Phi(t) (t^{-\zeta+1/2} e^{-\mathcal{I}^-(t)})' dt + \right. \\ \left. r^{-\zeta-1/2} e^{\mathcal{I}^+(r)} \int_r^b \Phi(t) (t^{\zeta+1/2} e^{-\mathcal{I}^+(t)})' dt \right] - \Phi(r) + O(\zeta^{-2})$$

(as  $\zeta \rightarrow +\infty$ ) for  $\mathcal{I}^\pm(r) \stackrel{\text{def}}{=} \int \frac{g \pm zr}{c^2} dr$ , respectively.



## Finding a Symmetric Operator

We notice that if  $z \frac{r}{c^2}$ ,  $\frac{\rho'}{\rho}$  are small (say  $z$  small and  $\ln \rho$  slowly varying) compared to  $\frac{1}{r}$ , then  $y_\rho$  can be written as

$$y_\rho = \int_a^b W(r, t) \Phi(t) dt - \Phi(r) + \epsilon O(\zeta^{-1}) + O(\zeta^{-2})$$

where  $W(r, t)$  is a symmetric kernel.

Here,  $\epsilon$  is small if  $\mathcal{I}^\pm$  and their derivatives are uniformly small.

## Case for Sharper Estimates

Then,

- Consider

$$\frac{\rho r^2}{c^2} = \frac{\rho(r_0)r_0^2}{c^2(r_0)} + O(|r - r_0|)$$

- equation (6) becomes of the familiar general form

$$\mathcal{L}\Phi = F(\Phi) + f_0$$

- resulting in  $\|\Phi_p\| \leq \frac{1}{\gamma} (C_1 + C_2(\zeta^{-1}) + C_3\|\eta_0\|)$
- with  $\gamma^{-1} = O(\zeta^{-2})$ .
- $C_1$  is small if  $\frac{\rho r^2}{c^2}$  is slowly varying on  $(a, b)$ .

# A Relativistic Pulsation Model

Taking from Lindblom, Mendell, Ipser [LMI]: Regge-Wheeler gauge whereby the metric perturbation is given by

$$(g_{ab} + \delta g_{ab}) dx^a dx^b = \\ -e^\nu (1 - H_0 Y_\ell^m e^{i\sigma t}) dt^2 + 2iH_1 Y_\ell^m e^{i\sigma t} dt dr + e^\lambda (1 - H_0 Y_\ell^m e^{i\sigma t}) dr^2 \\ + r^2 (1 - KY_\ell^m e^{i\sigma t}) (d\theta^2 + \sin^2 \theta d\phi^2)$$

Barotropic (Eulerian) perturbations

$$\delta\rho = \frac{d\rho}{dP} \delta P Y_m^\ell e^{i\sigma t}$$

Speed of light and  $G$  equal to 1, even parity

- $H_1$  and  $K$  expressed in terms of  $H_0$  and  $\delta U = \frac{\delta P}{\rho + P} + H_0/2$
- Transformation involved generally may have singularities
- Consider weak field and slow rotation.

$$\begin{aligned}\delta U'' + \left( \frac{2}{r} - \frac{\nu'}{2} \frac{d\rho}{dP} + v_1 \right) \delta U' + \left[ \frac{\sigma^2}{e^\nu} \frac{d\rho}{dP} - \frac{\ell(\ell+1)}{r^2} + v_2 \right] e^\lambda \delta U \\ = v_3 H'_0 + \left[ \frac{\sigma^2}{2e^\nu} \frac{d\rho}{dP} + v_4 \right] e^\lambda H_0;\end{aligned}$$

$$\begin{aligned}H''_0 + \left( \frac{2}{r} + \eta_1 \right) H'_0 + \left[ \frac{\sigma^2}{e^\nu} - \frac{\ell(\ell+1)}{r^2} + 4\pi(P + \rho) \frac{d\rho}{dP} + \eta_2 \right] e^\lambda H_0 \\ = \eta_3 \delta U' + \left[ 8\pi(P + \rho) \frac{d\rho}{dP} + \eta_4 \right] e^\lambda \delta U\end{aligned}$$

- $\frac{M}{R}, \sigma, \frac{P}{\rho} < \epsilon \ll 1$
- Replace  $H_0 = 2\Phi$  and  $\delta U = 2\sigma^2\eta$
- Modulo  $O(\epsilon)$ :  $\nu' = -2\frac{P'}{\rho}$ ,  $P' = -\rho g$ ,  $\frac{d\rho}{dP} = 1/c^2$
- $v_j = \eta_j = O(\epsilon)$

$$\mathcal{L}_\ell\Phi + (v_1 + O(\epsilon))\Phi' + (v_2 + O(\epsilon))\Phi = v_3\eta' + \left(\frac{4\pi\sigma^2 r^2 \rho}{c^2} + v_4 + O(\epsilon)\right)\eta$$

$$\mathcal{J}_\ell\eta + (\eta_1 + O(\epsilon))\eta' + (\eta_2 + O(\epsilon))\eta = \eta_3\Phi' + \left(\frac{r^2\rho}{c^2} + \eta_4 + O(\epsilon)\right)\Phi$$

## ES Formulation to Order $\epsilon$

Integrating factors  $e^{\nu_1 \frac{r^2}{\rho}}$  and  $e^{\eta_1 \frac{r^2}{\rho}}$  respectively yield

$$\mathcal{J}^\# \eta = \left( \frac{r^2 \rho}{c^2} + O(\epsilon) \right) \Phi + O(\epsilon) \Phi'$$

$$\mathcal{L}^\# \Phi = \left( 4\pi \sigma^2 \frac{r^2 \rho}{c^2} + O(\epsilon) \right) \eta + O(\epsilon) \eta'$$

to form

$$\mathcal{L}^\# \Phi = \sigma^2 F^\#(\Phi) + \sigma^2 f_0$$

with  $\mathcal{L}^\#$  S-L,  $F^\#$  symmetric, and  $\|f_0\| \leq C\|\eta_0\| + O(\epsilon)\|\Phi\|$

Likewise,

$$\|\Phi\| \leq \frac{\sigma^2 \text{Const}}{\gamma} \|\eta_0\|$$

# Summary

- The Cowling approximation appears to be verified under certain conditions in the case of adiabatic equilibrium.
- We find particular  $\Phi_p$  small in norm for large degree compared to certain other homogeneous dependent variables.
- Analysis can apply to relativistic pulsation if approximately Newtonian.





# Outlook

## Continuation:





- Search for failures of Cowling approximation: Use method in reverse to find  $\Phi_p$  relatively large.
- Extend to cases of stable equilibrium  $N^2 > 0$  (against convection) - perhaps a perturbation of present case.
- What if eigenvalues are nested?
- Study spectral distance and resulting estimates as they depend on length of interval  $(a, b)$ .
- Involve various order-of-magnitude estimates of physical quantities: Determine practicalities of method.
- Some non-linear pulsation models may perhaps be investigated by further application of results of [A].






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Below are Mathematica works involving is asymptotic estimates used.

# Asymptotics for Large parameter in a Newtonian Stellar Pulsation Model 1:

We develop asymptotic estimates for a system of the form

$$Y' [t] = \rho \mathcal{A}_0 Y + \mathcal{A}_1 Y + \rho^{-1} \mathcal{A}_2 Y$$

for large real parameter  $\rho$ . The matrices in this case are given:

```
In[261]:=  $\mathcal{A}0 = t^{-1} * \{\{\theta, 1/z\}, \{z, \theta\}\};$   
MatrixForm[%]
```

Out[262]/MatrixForm=

$$\begin{pmatrix} \theta & \frac{1}{z} \\ z & \theta \end{pmatrix}$$

```
In[263]:=  $\mathcal{A}1 = \{\{(t * g[t] - (c[t])^2) / (t * (c[t])^2), -t / (c[t])^2\}, \{\theta, \theta\}\};$   
MatrixForm[%]
```

Out[264]/MatrixForm=

$$\begin{pmatrix} \frac{-c[t]^2 + t g[t]}{t c[t]^2} & -\frac{t}{c[t]^2} \\ \theta & \theta \end{pmatrix}$$

```
In[265]:=  $\mathcal{A}2 = \{\{\theta, \theta\}, \{\theta, \theta\}\};$   
MatrixForm[%]
```

Out[266]/MatrixForm=

$$\begin{pmatrix} \theta & \theta \\ \theta & \theta \end{pmatrix}$$

We now diagonalize the leading matrix and convert the differential system to the form

$$X' = \rho A_0 X + A_1 X + \rho^{-1} A_2 X \text{ for } Y = PX.$$

```
In[267]:=  $\{P, A0\} = \text{JordanDecomposition}[\mathcal{A}0]$   
 $A1 = \text{Inverse}[P] . \mathcal{A}1 . P - \text{Inverse}[P] . D[P, t]$   
 $A2 = \text{Inverse}[P] . \mathcal{A}2 . P;$ 
```

```
Out[267]= {{{{-1/z, 1/z}, {1, 1}}, {{{-1/t, 0}, {0, 1/t}}}}
```

```
Out[268]= {{{{t z / (2 c[t]^2) + (-c[t]^2 + t g[t]) / (2 t c[t]^2), t z / (2 c[t]^2) - (-c[t]^2 + t g[t]) / (2 t c[t]^2)},  
{-t z / (2 c[t]^2) - (-c[t]^2 + t g[t]) / (2 t c[t]^2), -t z / (2 c[t]^2) + (-c[t]^2 + t g[t]) / (2 t c[t]^2)}}}}
```

Our goal is to follow [CL] to develop asymptotic estimates for a fundamental solution M for the in the form

$$\mathcal{F} = e^{\rho Q_0 + Q_1} (I + \rho^{-1} P_1 + \rho^{-2} P_2)$$

The matrices in the exponent are diagonal where none of the Q's or P's depend on parameter  $\rho$ . The procedure, broadly speaking, is to solve the differential equation formally in equating terms of formal series in the parameter  $\rho$  in substituting into the asymptotic expression into the differential equation: Off-diagonal terms (Offdiag[]) and on-diagonal (Ondiag[]) terms for the P's are solve separately. To do this we produce matrices with undetermined coefficients and solve for them either via Solve[] or DSolve[] and substitute the solutions accordingly. We will impose a condition at  $t = 1$  in our integration steps.

```
In[270]:= Pmtc[n_] := Array[PeIs, {4, 2, 2}][[n]]
Pmtc0 = IdentityMatrix[2]
Qpmtx[n_] := DiagonalMatrix[Array[Qprm, {2, 1, 2}][[n]][[1]]]
Offdiag[a_] := a - DiagonalMatrix[Diagonal[a]]
Ondiag[a_] := DiagonalMatrix[Diagonal[a]]
```

```
Out[271]= {{1, 0}, {0, 1}}
```

We solve the off-diagonal terms of  $P_1$  and the  $Q_0$  terms:

```
In[275]:= Q0 = Integrate[A0, t]
LHS0 = Pmtc0.Qpmtx[1] + Pmtc[1].A0;
RHS0 = A0.Pmtc[1] + A1.Pmtc0;
sol1 = Solve[{Offdiag[LHS0] == Offdiag[RHS0]},
  Complement[Flatten[Pmtc[1]], Diagonal[Pmtc[1]]]];
NewPeIs[i_, j_] := If[i != j, Pmtc[1][[i, j]] /. sol1[[1]], Pmtc[1][[i, j]][t]];
NewPmtc = Array[NewPeIs, {2, 2}]
SolQ1 = Solve[Ondiag[LHS0] == Ondiag[RHS0], Diagonal[Qpmtx[1]]]
NewQmtx1 = Qpmtx[1] /. SolQ1[[1]];
Q1 = Integrate[NewQmtx1, t]
```

```
Out[275]= {{-Log[t], 0}, {0, Log[t]}}
```

```
Out[280]= {{PeIs[1, 1, 1][t],  $\frac{t^2 z + c[t]^2 - t g[t]}{4 c[t]^2}$ }, { $\frac{t^2 z - c[t]^2 + t g[t]}{4 c[t]^2}$ , PeIs[1, 2, 2][t]}}
```

```
Out[281]= {{Qprm[1, 1, 1] ->  $\frac{t^2 z - c[t]^2 + t g[t]}{2 t c[t]^2}$ , Qprm[1, 1, 2] ->  $\frac{-t^2 z - c[t]^2 + t g[t]}{2 t c[t]^2}$ }}
```

```
Out[283]= {{ $\frac{1}{2} \int \frac{t^2 z - c[t]^2 + t g[t]}{t c[t]^2} dt$ , 0}, {0,  $\frac{1}{2} \int \frac{-t^2 z - c[t]^2 + t g[t]}{t c[t]^2} dt$ }}
```

We now complete  $P_1$  and solve the off-diagonal terms for  $P_2$ :

```

In[284]:= LHS1 = D[NewPmtx, t] + NewPmtx.NewQmtx1 + Pmtc[2].A0;
RHS1 = A1.NewPmtx + A0.Pmtc[2] + A2;
eqn1 = Simplify[Diagonal[LHS1] - Diagonal[RHS1]];
initvals = Diagonal[NewPmtx] /. t -> 1;
sol1b = DSolve[{eqn1 == {0, 0}, initvals == {0, 0}}, Diagonal[NewPmtx], t];
P1 = NewPmtx /. Flatten[sol1b]
Sol2 = Solve[Offdiag[LHS1] == Offdiag[RHS1],
  Complement[Flatten[Pmtc[2]], Diagonal[Pmtc[2]]] /. sol1b[[1]] /. sol1[[1]];
NewP1els2[i_, j_] := If[i != j, Pmtc[2][[i, j]] /. Flatten[Sol2], Pmtc[2][[i, j]][t]];
NewPmtx2 = Array[NewP1els2, {2, 2}];

```

$$\text{Out[289]= } \left\{ \left\{ \int_1^t \frac{-c[K[1]]^4 + 2c[K[1]]^2 g[K[1]] \times K[1] - g[K[1]]^2 K[1]^2 + z^2 K[1]^4}{8c[K[1]]^4 K[1]} dK[1], \right. \right. \\ \left. \left. \frac{t^2 z + c[t]^2 - t g[t]}{4c[t]^2} \right\}, \left\{ \frac{t^2 z - c[t]^2 + t g[t]}{4c[t]^2}, \right. \right. \\ \left. \left. \int_1^t \frac{c[K[2]]^4 - 2c[K[2]]^2 g[K[2]] \times K[2] + g[K[2]]^2 K[2]^2 - z^2 K[2]^4}{8c[K[2]]^4 K[2]} dK[2] \right\} \right\}$$

We complete  $P_2$  as we find the diagonal terms. We have introduced a matrix  $P_3$  but we do not compute any of the since any terms involve them on the diagonals cancel from the equation.

```

In[293]:= LHS2 = D[NewPmtx2, t] + NewPmtx2.D[Q1, t] + Pmtc[3].A0;
RHS2 = A1.NewPmtx2 + A0.Pmtc[3] + A2.P1;
eqn2 = Simplify[Diagonal[LHS2] - Diagonal[RHS2]];
initvals2 = Diagonal[NewPmtx2] /. t -> 1;
sol2b = DSolve[{eqn2 == {0, 0}, initvals2 == {0, 0}}, Diagonal[NewPmtx2], t];
P2 = NewPmtx2 /. Flatten[sol2b];

```

As a test of our work thus far, we substitute the expression into the derived equation. The difference of the two sides should be of order  $O(\rho^{-2})$

```

In[299]:= Formal = (Pmtc0 + rho^(-1) P1 + rho^(-2) P2).MatrixExp[rho * Q0 + Q1];
Series[Simplify[D[Formal, t] - (rho * A0 + A1 + rho^(-1) A2).Formal], {rho, Infinity, 1}]
Series[Simplify[D[Formal, t] - (rho * A0 + A1 + rho^(-1) A2).Formal], rho -> 0];

```

$$\text{Out[300]= } \left\{ \left\{ \theta, e^{\frac{1}{2} \text{Integrate}\left[-\frac{1}{t} + \frac{t z g[t]}{c[t]^2}, t, \text{Assumptions} \rightarrow \text{Re}[\rho] > 4096 \&\& -\frac{1}{4096} < \text{Im}[\rho] < \frac{1}{4096}\right] + \left(\text{Log}[t] \rho - \text{Log}[t] + O\left[\frac{1}{\rho}\right]^2\right)} O\left[\frac{1}{\rho}\right]^2 \right\}, \right. \\ \left. \left\{ e^{\frac{1}{2} \left(\text{Integrate}\left[-\frac{1}{t} + \frac{t z g[t]}{c[t]^2}, t, \text{Assumptions} \rightarrow \text{Re}[\rho] > 4096 \&\& -\frac{1}{4096} < \text{Im}[\rho] < \frac{1}{4096}\right] + (-2 \text{Log}[t] \rho - 2 \text{Log}[t] + O\left[\frac{1}{\rho}\right]^2)\right)} O\left[\frac{1}{\rho}\right]^2, \theta \right\} \right\}$$

We also test the formal solution by verifying that coefficients cancel  $\rho^{-k}$  in the differential equation for  $k = 1, 2$  which involve the solved terms.

```

In[302]:= TestLHS1 = D[P1, t] + P1.D[Q1, t] + P2.A0;
TestRHS1 = A1.P1 + A0.P2 + A2;
Testeqn1 = Simplify[TestLHS1 - TestRHS1]

```

$$\text{Out[304]= } \left\{ \{0, 0\}, \{0, 0\} \right\}$$

```
In[305]= P3 = Pmtc[3];
TestLHS2 = Ondiag[D[P2, t] + P2.D[Q1, t] + P3.D[Q0, t]];
TestRHS2 = Ondiag[A1.P2 + A0.P3 + A2.P1];
Simplify[TestLHS2 - TestRHS2]
```

```
Out[308]= {{0, 0}, {0, 0}}
```

We obtain our asymptotic estimate  $\mathcal{P}\mathcal{F}$  for the original system and list the corresponding exponential terms along with correction terms  $PP$ :

```
In[309]= Asympt = P.Formal;
```

```
In[310]= Coefficient[Asympt, ρ, 0]
Coefficient[Asympt, ρ, -1] / Coefficient[Asympt, ρ, 0];
Coefficient[Asympt, ρ, -2] / Coefficient[Asympt, ρ, 0];
```

```
Out[310]= { { -  $\frac{e^{\frac{1}{2} \int \frac{t^2 z - c[t]^2 + t g[t]}{t c[t]^2} dt}}{z} t^{-\rho}$ ,  $\frac{e^{\frac{1}{2} \int \frac{-t^2 z - c[t]^2 + t g[t]}{t c[t]^2} dt}}{z} t^{\rho}$  }, {  $e^{\frac{1}{2} \int \frac{t^2 z - c[t]^2 + t g[t]}{t c[t]^2} dt} t^{-\rho}$ ,  $e^{\frac{1}{2} \int \frac{-t^2 z - c[t]^2 + t g[t]}{t c[t]^2} dt} t^{\rho}$  } }
```



# Asymptotics for Large parameter In a Newtonian Stellar Pulsation Model 2:

We develop asymptotic estimates for a system of the form

$$Y' [t] = \sigma \mathcal{A}_0 Y + \mathcal{A}_1 Y + \sigma^{-1} \mathcal{A}_2 Y$$

for large real parameter  $\sigma$ . The matrices in this case are given:

In[209]:=  $\mathcal{A}0 = \{\{\mathbf{0}, -\rho[t] t^2 / c[t]^2\}, \{1 / (\rho[t] t^2), \mathbf{0}\}\};$   
**MatrixForm[%]**

Out[210]//MatrixForm=

$$\begin{pmatrix} \mathbf{0} & -\frac{t^2 \rho[t]}{c[t]^2} \\ \frac{1}{t^2 \rho[t]} & \mathbf{0} \end{pmatrix}$$

In[211]:=  $\mathcal{A}1 = \{\{\mathbf{0}, \mathbf{0}\}, \{\mathbf{0}, \mathbf{0}\}\};$   
**MatrixForm[%]**

Out[212]//MatrixForm=

$$\begin{pmatrix} \mathbf{0} & \mathbf{0} \\ \mathbf{0} & \mathbf{0} \end{pmatrix}$$

In[213]:=  $\mathcal{A}2 = \{\{\mathbf{0}, \rho[t] * L\}, \{\mathbf{0}, \mathbf{0}\}\};$   
**MatrixForm[%]**

Out[214]//MatrixForm=

$$\begin{pmatrix} \mathbf{0} & L \rho[t] \\ \mathbf{0} & \mathbf{0} \end{pmatrix}$$

We now diagonalize the leading matrix and convert the differential system to the form

$$X' = \sigma A_0 X + A_1 X + \sigma^{-1} A_2 X$$

for  $Y = PX$ .

In[215]:=  $\{P, A0\} = \text{JordanDecomposition}[\mathcal{A}0]$   
 $A1 = \text{Inverse}[P] . \mathcal{A}1 . P - \text{Inverse}[P] . D[P, t];$   
 $A2 = \text{Inverse}[P] . \mathcal{A}2 . P;$

Out[215]=  $\{\{\{-\frac{i t^2 \rho[t]}{c[t]}, \frac{i t^2 \rho[t]}{c[t]}\}, \{1, 1\}\}, \{\{-\frac{i}{c[t]}, \mathbf{0}\}, \{\mathbf{0}, \frac{i}{c[t]}\}\}\}$

Our goal is to follow [CL] to develop asymptotic estimates for a fundamental solution M for the in the form

$$\mathcal{F} = e^{\sigma Q_0 + Q_1} (I + \sigma^{-1} P_1 + \sigma^{-2} P_2)$$

The matrices in the exponent are diagonal where none of the Q's or P's depend on parameter  $\sigma$ . The procedure is, broadly speaking, is to solve

the differential equation formally in equating terms of formal series in the parameter  $\sigma$  in substituting

into the asymptotic expression into the differential equation: Off-diagonal terms (`Offdiag[]`) and on-diagonal (`Ondiag[]`) terms for the  $P$ 's are solve separately. To do this we produce matrices with undetermined coefficients and solve for them either via `Solve[]` or `DSolve[]` and substitute the solutions accordingly. We will impose a condition at  $t = 1$  in our integration steps.

```
In[218]:= Pmtc[n_] := Array[PeIs, {4, 2, 2}][[n]]
Pmtc0 = IdentityMatrix[2]
Qpmtx[n_] := DiagonalMatrix[Array[Qprm, {2, 1, 2}][[n]][[1]]]
Offdiag[a_] := a - DiagonalMatrix[Diagonal[a]]
Ondiag[a_] := DiagonalMatrix[Diagonal[a]]
```

```
Out[219]= {{1, 0}, {0, 1}}
```

We solve the off-diagonal terms of  $P_1$  and the  $Q_0$  terms:

```
In[223]:= Q0 = Integrate[A0, t]
LHS0 = Pmtc0.Qpmtx[1] + Pmtc[1].A0;
RHS0 = A0.Pmtc[1] + A1.Pmtc0;
sol1 = Solve[Offdiag[LHS0] == Offdiag[RHS0],
  Complement[Flatten[Pmtc[1]], Diagonal[Pmtc[1]]]];
NewPeIs[i_, j_] := If[i != j, Pmtc[1][[i, j]] /. sol1[[1]], Pmtc[1][[i, j]][t]];
NewPmtx = Array[NewPeIs, {2, 2}]
SolQ1 = Solve[Ondiag[LHS0] == Ondiag[RHS0], Diagonal[Qpmtx[1]]]
NewQmtx1 = Qpmtx[1] /. SolQ1[[1]];
Q1 = Integrate[NewQmtx1, t]
```

```
Out[223]= {{-i ∫ 1/c[t] dt, 0}, {0, i ∫ 1/c[t] dt}}
```

```
Out[228]= {{PeIs[1, 1, 1][t], i (-2 c[t] × ρ[t] + t ρ[t] c'[t] - t c[t] ρ'[t]) / (4 t ρ[t])},
  {i (2 c[t] × ρ[t] - t ρ[t] c'[t] + t c[t] ρ'[t]) / (4 t ρ[t]), PeIs[1, 2, 2][t]}}
```

```
Out[229]= {{Qprm[1, 1, 1] → (-2 c[t] × ρ[t] + t ρ[t] c'[t] - t c[t] ρ'[t]) / (2 t c[t] × ρ[t]),
  Qprm[1, 1, 2] → (-2 c[t] × ρ[t] + t ρ[t] c'[t] - t c[t] ρ'[t]) / (2 t c[t] × ρ[t])}}
```

```
Out[231]= {{-Log[t] + 1/2 Log[c[t]] - 1/2 Log[ρ[t]], 0}, {0, -Log[t] + 1/2 Log[c[t]] - 1/2 Log[ρ[t]}}
```

We now complete  $P_1$  and solve the off-diagonal terms for  $P_2$ :

```

In[232]:= LHS1 = D[NewPmtx, t] + NewPmtx.NewQmtx1 + Pmtc[2].A0;
RHS1 = A1.NewPmtx + A0.Pmtc[2] + A2;
eqn1 = Simplify[Diagonal[LHS1] - Diagonal[RHS1]];
initvals = Diagonal[NewPmtx] /. t -> 1;
sol1b = DSolve[{eqn1 == {0, 0}, initvals == {0, 0}}, Diagonal[NewPmtx], t];
P1 = NewPmtx /. Flatten[sol1b]
Sol2 = Solve[Offdiag[LHS1] == Offdiag[RHS1],
  Complement[Flatten[Pmtc[2]], Diagonal[Pmtc[2]]] /. sol1b[[1]] /. sol1[[1]];
NewP1els2[i_, j_] := If[i != j, Pmtc[2][[i, j]] /. Flatten[Sol2], Pmtc[2][[i, j]][t]];
NewPmtx2 = Array[NewP1els2, {2, 2}];

```

$$\text{Out[237]= } \left\{ \left\{ \int_1^t \left( i \left( 4 c[K[1]]^2 \rho[K[1]]^2 + 4 L c[K[1]]^2 \rho[K[1]]^2 - 4 c[K[1]] \times K[1] \rho[K[1]]^2 c'[K[1]] + \right. \right. \right. \\
\left. \left. \left. K[1]^2 \rho[K[1]]^2 c'[K[1]]^2 + 4 c[K[1]]^2 K[1] \times \rho[K[1]] \rho'[K[1]] - \right. \right. \right. \\
\left. \left. \left. 2 c[K[1]] K[1]^2 \rho[K[1]] c'[K[1]] \rho'[K[1]] + c[K[1]]^2 K[1]^2 \rho'[K[1]]^2 \right) \right) / \right. \\
\left. \left( 8 c[K[1]] K[1]^2 \rho[K[1]]^2 \right) dK[1], \frac{i \left( -2 c[t] \times \rho[t] + t \rho[t] c'[t] - t c[t] \rho'[t] \right)}{4 t \rho[t]} \right\}, \\
\left\{ \frac{i \left( 2 c[t] \times \rho[t] - t \rho[t] c'[t] + t c[t] \rho'[t] \right)}{4 t \rho[t]}, \right. \\
\left. \int_1^t \left( i \left( -4 c[K[2]]^2 \rho[K[2]]^2 - 4 L c[K[2]]^2 \rho[K[2]]^2 + 4 c[K[2]] \times K[2] \rho[K[2]]^2 c'[K[2]] - \right. \right. \right. \\
\left. \left. \left. K[2]^2 \rho[K[2]]^2 c'[K[2]]^2 - 4 c[K[2]]^2 K[2] \times \rho[K[2]] \rho'[K[2]] + \right. \right. \right. \\
\left. \left. \left. 2 c[K[2]] K[2]^2 \rho[K[2]] c'[K[2]] \rho'[K[2]] - c[K[2]]^2 K[2]^2 \rho'[K[2]]^2 \right) \right) / \right. \\
\left. \left( 8 c[K[2]] K[2]^2 \rho[K[2]]^2 \right) dK[2] \right\}$$

We complete  $P_2$  as we find the diagonal terms. We have introduced a matrix  $P_3$  but we do not compute any of the since any terms involve them on the diagonals cancel from the equation.

```

In[241]:= LHS2 = D[NewPmtx2, t] + NewPmtx2.D[Q1, t] + Pmtc[3].A0;
RHS2 = A1.NewPmtx2 + A0.Pmtc[3] + A2.P1;
eqn2 = Simplify[Diagonal[LHS2] - Diagonal[RHS2]];
initvals2 = Diagonal[NewPmtx2] /. t -> 1;
sol2b = DSolve[{eqn2 == {0, 0}, initvals2 == {0, 0}}, Diagonal[NewPmtx2], t];
P2 = NewPmtx2 /. Flatten[sol2b];

```

As a test of our work thus far, we substitute the expression into the derived equation. The difference of the two sides should be of order  $O(\sigma^2)$

```

In[247]:= Formal = (Pmtc0 + sigma^(-1) P1 + sigma^(-2) P2).MatrixExp[sigma * Q0 + Q1];
Series[Simplify[D[Formal, t] - (sigma * A0 + A1 + sigma^(-1) A2).Formal], {sigma, Infinity, 1}]
Series[Simplify[D[Formal, t] - (sigma * A0 + A1 + sigma^(-1) A2).Formal], sigma -> 0];

```

$$\text{Out[248]= } \left\{ \left\{ e^{\int \frac{1}{c[t]}, t, \text{Assumptions} \rightarrow \text{Re}[\sigma] > 4096 \&\& - \frac{1}{4096} < \text{Im}[\sigma] < \frac{1}{4096}} \left( -i \sigma + 0 \left[ \frac{1}{\sigma} \right]^2 \right) O \left[ \frac{1}{\sigma} \right]^3, \right. \right. \\
\left. \left. e^{\int \frac{1}{c[t]}, t, \text{Assumptions} \rightarrow \text{Re}[\sigma] > 4096 \&\& - \frac{1}{4096} < \text{Im}[\sigma] < \frac{1}{4096}} \left( i \sigma + 0 \left[ \frac{1}{\sigma} \right]^2 \right) O \left[ \frac{1}{\sigma} \right]^2 \right\}, \right. \\
\left\{ e^{\int \frac{1}{c[t]}, t, \text{Assumptions} \rightarrow \text{Re}[\sigma] > 4096 \&\& - \frac{1}{4096} < \text{Im}[\sigma] < \frac{1}{4096}} \left( -i \sigma + 0 \left[ \frac{1}{\sigma} \right]^2 \right) O \left[ \frac{1}{\sigma} \right]^2, \right. \\
\left. \left. e^{\int \frac{1}{c[t]}, t, \text{Assumptions} \rightarrow \text{Re}[\sigma] > 4096 \&\& - \frac{1}{4096} < \text{Im}[\sigma] < \frac{1}{4096}} \left( i \sigma + 0 \left[ \frac{1}{\sigma} \right]^2 \right) O \left[ \frac{1}{\sigma} \right]^3 \right\} \right\}$$

We also test the formal solution by verifying that term cancel in powers of  $i - 1$  th of  $\sigma$  in the differential equation for  $i = 1, 2$  which involve the solved terms.

```
In[250]:= TestLHS1 = D[P1, t] + P1.D[Q1, t] + P2.A0;
TestRHS1 = A1.P1 + A0.P2 + A2;
Testeqn1 = Simplify[TestLHS1 - TestRHS1]
```

```
Out[252]= {{0, 0}, {0, 0}}
```

```
In[253]:= P3 = Pmtc[3];
TestLHS2 = Ondiag[D[P2, t] + P2.D[Q1, t] + P3.D[Q0, t]];
TestRHS2 = Ondiag[A1.P2 + A0.P3 + A2.P1];
Simplify[TestLHS2 - TestRHS2]
```

```
Out[256]= {{0, 0}, {0, 0}}
```

We obtain our asymptotic estimate  $\mathcal{P}\mathcal{F}$  for the original system and list the corresponding exponential terms along with correction terms  $PP$ :

```
In[257]:= Asympt = P.Formal;
```

```
In[258]:= Coefficient[Asympt,  $\sigma$ , 0]
Coefficient[Asympt,  $\sigma$ , -1] / Coefficient[Asympt,  $\sigma$ , 0];
Coefficient[Asympt,  $\sigma$ , -2] / Coefficient[Asympt,  $\sigma$ , 0];
```

```
Out[258]= { { -  $\frac{i e^{-i \sigma \int \frac{1}{c[t]} dt} t \sqrt{\rho[t]}}{\sqrt{c[t]}}$ ,  $\frac{i e^{i \sigma \int \frac{1}{c[t]} dt} t \sqrt{\rho[t]}}{\sqrt{c[t]}}$  }, {  $\frac{e^{-i \sigma \int \frac{1}{c[t]} dt} \sqrt{c[t]}}{t \sqrt{\rho[t]}}$ ,  $\frac{e^{i \sigma \int \frac{1}{c[t]} dt} \sqrt{c[t]}}{t \sqrt{\rho[t]}}$  } }
```